Trucking's Future Now

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Text Questions for the Speakers to: 862-781-0001.



ELECTRICITY MAY BE THE DEVER. One day your car may speed along an electric super-highway, its speed and steering automatically controlled by electronic devices embedded in the road. Travel will be more enjoyable. Highways will be made safe - by electricity! No traffic jame . . . no collisions on driver fatigue.

Driverless Car of the Future, advertisement for "America's Electric Light and Power Companies," Saturday Evening Post, 1950s. Credit: The Everett Collection.



Mercedes-Benz F 015



Level 0	No automation	
Level 1	Adaptive cruise control, auto windshield wipers, automatic lights, anything that supports the driver (e.g. ESC, V2V)	TRANSP RESEARCH UNIVERSITY
Level 2	Hands off and feet off but eyes on. Driver is responsible - Low speed congested traffic	
Level 3	Hands off feet off eyes off – shared dual control but <i>vehicle is responsible</i>	
Level 4	Complete machine control – <i>Driver has no</i> responsibility at all	

VSTITU

NHTSA Levels of Autonomy



No-Automation (Level 0): The driver is in complete and sole control of the primary vehicle controls - brake, steering, throttle, and motive power - at all times.



Function-specific Automation (Level 1): Automation at this level involves one or more specific control functions. Examples include electronic stability control or pre-charged brakes, where the vehicle automatically assists with braking to enable the driver to regain control of the vehicle or stop faster than possible by acting alone.

Combined Function Automation (Level 2): This level involves automation of at least two primary control functions designed to work in unison to relieve the driver of control of those functions. An example of combined functions enabling a Level 2 system is adaptive cruise control in combination with lane centering.

Limited Self-Driving Automation (Level 3): Vehicles at this level of automation enable the driver to cede full control of all safety-critical functions under certain traffic or environmental conditions and in those conditions to rely heavily on the vehicle to monitor for changes in those conditions requiring transition back to driver control. The driver is expected to be available for occasional control, but with sufficiently comfortable transition time. The Google car is an example of limited self-driving automation.

Full Self-Driving Automation (Level 4): The vehicle is designed to perform all safety-critical driving functions and monitor roadway conditions for an entire trip. Such a design anticipates that the driver will provide destination or navigation input, but is not expected to be available for control at any time during the trip. This includes both occupied and unoccupied vehicles.

	Levels of Autonomy	Existing Examples
1 Driver only	The vehicle is entirely under human control but may have some automated systems.	Cruise control, electronic stability control, anti-lock brakes
2 Driver assistance	The steering and/or acceleration are automated but the driver must control the other functions.	Adaptive cruise control: distance to car in front maintained. Parking assistant: steering is automated, driver controls accelerator and brakes.
3 Partial autonomy	The driver does not control steering or acceleration but is expected to be attentive at all times and take back control instantaneously when required.	Adaptive cruise control with lane keeping. Traffic jam assistance.
4 High autonomy	Vehicles are able to operate autonomously for some portions of the journey. Transfer of control back to the human driver happens with some warning.	Prototype vehicles.
5 Full autonomy	The vehicle is capable of driving unaided for the entire journey with no human intervention – potentially without a human in the car.	None

 Table 1: Adapted from Autonomous Road Vehicles - POSTnote 443, September 2013, Dr Chandrika Nath,

 Parliamentary Office of Science and Technology, Parliamentary Copyright 2013





Puget Sound Regional Council

Autonomous Car Interest Questions	Not a Intere	t all sted	Somewhat Uninterested	N	leutral	So Int	mewhat terested	Very Inter	ested	Don't Know
Taking a taxi ride in an autonomous car without a driver		39%	8%		15%		19%	9	%	10%
Commuting alone using an autonomous vehicle		38%	6%		12%		18%	16	%	10%
Riding in an autonomous car for a short trip to get to a vehicle		34%	5%		12%		23%	16	%	10%
Autonomous Car Concern Questions	Not at Conce	t all erned	Somewhat Unconcerned		Neutral	So Co	mewhat ncerned	Very Conc	erned	Don't Know
Equipment and system safety	7%		4%		13%		26%		39%	11%
Capability to react to the environment	7%		3%		9 %		22%		48%	11%
Legal Liability of drivers or owners	7%		4%		13%		27%		38%	11%



Trucking's Future Now

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Peloton Technology

DEREK ROTZ

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EQUIPMENT/TECHNOLOGY



Trucking's Future Now

JOSHUA SWITKES CEO Peloton Technology



EQUIPMENT/TECHNOLOGY



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Prevent Accidents Save Fuel by Connecting Trucks







Connecting Trucks

Radar



Real-time Cloud Supervision Platooning Only: When Safe Where Safe **Correctly Ordered Dynamic Adjustment to Conditions**

Wireless Link **Cloud Optimizations** Platooning **Active Braking Systems Linked Both Drivers Steer**

Both Trucks Save Fuel

#CVOUTLOOK

Rada

Cloud Hazard Alerts

Active Braking

Always On



Integrations



Michigan Meritor-Wabco Volvo Freightliner





CA, NV, UT, AZ, NM, TX Meritor-Wabco Peterbilt

OH, FL Bendix Peterbilt Kenworth



Trucking's Future Now

BILL KAHN Principal Engineer / Manager Peterbilt Motors



EQUIPMENT/TECHNOLOGY



Text Questions for the Speakers to: 862-781-0001.

DOE SuperTruck

Electrical **Idle Reduction** Aerodynamics Power Distribution • Li Ion Charge Start EPIQ Tractor Aero Package* High Speed Router SmartAir APU* Retractable Trailer Skirts 76% Freight Ton 66% Fuel 2 Driveline Economy Improvement Economy Downsped Transmission* Aluminum Driveline* Improvement **Rear Axle Powertrain** 6 X 2 Tandem w/ eTrac* Cummins 15L High Chassis Lightweight Axle Housings* Efficiency ISX Engine* Variable Gage Steel Rails Integrated Air Dampers Waste Heat Recovery Magnesium Crossmembers Ceramic Brake Drums Predictive Cruise Control* Aluminum Fifth-wheel* Advanced Light Wheels



Peterbilt Model 579 EPIQ







Fuel Efficiency

APEX Powertrain

Aerodynamics

Predictive Cruise & Neutral Coast

Driver Performance Assistant



Advanced Powertrain Research

- Alternative Fuels
- Hybrids
- Turbines
- Fuel Cells
- 2-Stroke Diesel Engines





Technology Demonstrators



Model 386 Aero 2 Package



Lightweight Optimization



HD Hybrid Development



Electrified A/C Condenser



Corvus Energy Demo



2012 & 2014 Tech Truck









Peterbilt Advanced Driver Assist Systems



Autonomous Roadmap



Trucking's Future Now

DEREK ROTZ Director, Advanced Engineering Daimler Trucks North America LLC



EQUIPMENT/TECHNOLOGY



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Daimler's Vision for Safety

"The Road to Accident-free Driving"













Automated Driving Achieved by Full Vehicle Integration









Consistent National Approach to Enable Automated Driving









Trucking's Future Now

SANDEEP KAR Global Vice President, Automotive & Transportation Research

Frost & Sullivan



EQUIPMENT/TECHNOLOGY



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How OEMs Will Differentiate Their Brands in the Future

QUALITY & RELIABILITY COMFORT & CONFORT & CONVERSHIP CONVENIENCE CONTOR OF OWNERSHIP CONVENIENCE CONTOR OF OWNERSHIP CONVENIENCE	AUTOMATED MOBILITY	SUSTAINABILITY & ENVIRONMENT	ADVANCED SAFETY	SERVICE & MAINTENANCE	POWERTRAIN EFFICIENCY
QUALITY & RELIABILITY COMFORT & COMFORT & CONVERSHIP CONVENTIONCE HEAL Image: Convention of the second					
	ALTH , WELLNESS, WELLBEING	CONNECTIVITY & SMART	COST OF OWNERSHIP	COMFORT & CONVENIENCE	QUALITY & RELIABILITY
PRE 2010 Image: Constraint of the second	FUTURE	ΓΟΟΑΥ		E 2010	Image: Constraint of the second se

#CVOUTLOOK

Source: COMMERCIALIVEHICLE

Automated Driving- Comparative Benchmarking

Level of Automation	Level 1	Level 2	Truck Platooning	Level 3	Level 4	
Enabling Technology	None	Electric-hydraulic power steering (EHPS), electric braking systems (EBS), electronic throttle control, adaptive cruise control (ACC), advanced driver assistance systems (ADAS)	V2X, DSRC, integrated safety systems (ISS), cameras, sensors, ACC	Intersection assist, redundancy backup for connectivity, self-driving capability until driver takes over control	Multiple redundancies (hardware) and artificial intelligence (software)	
Incremental Cost to OEMs	\$0	\$5,000–\$10,000	\$5,000–\$10,000	\$20,000-\$25,000	\$30,000 +	
Year Expected	Today	~2010–2020	~2018–2022	~2021–2025	~ 2035 +	
Distance/ Duration of Automation	None	Low	Moderate	Moderate-High	High	
Driver Involvement	Very High	High	Moderate	Moderate-Low	None	
Vocation		Long-haul	Long-haul	Long-haul	Long-haul 🔵	
Application (Long-haul, Regional,	All	Regional	Regional	Regional 🕕	Regional 🕘	
Vocational)		Vocational	Vocational 🕒	Vocational	Vocational 🕘	
High						



Autonomous Commercial Vehicle Incremental Cost Analysis –Now to Level 3





The leap from semi- to highly automated will be simpler in comparison to the leap to fully automated driving (Level 4)

Level of Automation	Driver-assisted Level 2	Semi-automated Level 3	Fully Automated Level 4	
Automatic transmission	Required	Required	Required	
Throttle, steering, and braking automation	Optional	Required	Required	
Radar	Required	Required	Required	
Ultrasonic sensors	Optional	Required	Required	
Forward-looking camera	Required	Required	Required	
Rear-vision camera	Optional	Required	Required	
Surround-view camera	Optional	Required	Required	
Night vision	Optional	Optional	Required	
LIDAR	Optional	Optional	Required	
GPS and map-supported ADAS	Optional	Optional	Required	
Telematics (prognostics and diagnostics)	Optional	Required	Required	
Wireless and communication networks	Optional	Required	Required	
Artificial intelligence	Optional	Optional	Required	
Multiple redundancies	Optional	Optional	Required	
Self-healing systems	Optional	Optional	Required	





Implications on Human Factors



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Cybersecurity and Data Encryption- Absolute Necessity

Critical Vehicle Data

- Engine control unit
- Transmission control unit
- Body controllers (locks/lights)
- Air bag control unit
- Steering, suspension, and stability

Infotainment & Telematics

- Vehicle data from OBD II, GPS coordinates, driving patterns, diagnostics
- Internet, smartphone interfacing, Bluetooth, Wi-Fi, app store
- Radio and media streaming

Cybersecurity Attack Points



External Interfaces

- Keyless entry
- TPMS
- V2X communication/DSRC
- Satellite data
- Sensor and camera data

In the automated scenario, there is a high possibility of a vehicle being compromised. Drivers must be provided with a fail-safe switch to shut down ADAS systems to regain full control of the vehicle.

Dependence on an Internet network remains; the exchange of data must be managed properly. Encryption of data exchange will bring third-party security solution providers into the value chain.



Snapshot of Global Automated Truck Adoption, 2025 and 2035

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COMMERCIAL VEHICLE

Role of Big Data in Ushering a New Era in Trucking



Big Data Catalysis

- Fleets to obtain both panoramic and granular view of operating parameters
- **Proactive decision making** enabled by big data analytics
- Fuel, freight, driver, equipment efficiencies will be elevated
- New technologies and concepts will emerge-Automated mobility, Uber for trucks, prognostics, maintenance on the fly, innovative insurance models

Source: Frost & Sullivan analysis.



Uber for Trucks is Here- By 2025 \$26.4 Billion in Freight Transactions to Occur Through This Platform

25 Trucks, 25 Loads, One Day= 1,725 Empty Miles, Driver Fatigue, Traffic Congestion

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With Automated Matching System→ Empty Miles Reduced to 272, Less Tired Drivers, Less Traffic, Happy Shippers, Happy Fleets



If you scale this up to 2 Million Trucks in US that drive through US cities each day about 12 Billion Empty Miles Can be Reduced





What Does Not Meet the Eye- Impact of These Changes on Telematics and Connectivity Business





Talking About Things That Do Not Meet the Eye







Commercial Vehicle Outlook: Truck of the Future- What Will Be Its Attributes?







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